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	L25	0D	L25	ОТ		L250Q	
Electrical Specs	L250D	L250D-1S	L250T	L250T-1S	L250Q	L250Q-1S	L250Q-2S
Continuous Force ¹	34N (7.6lbs)		52N (11.7lbs)		69N (15.5lbs)		
Continuous Current ¹	1.3Arms	2.6Arms	1.3Arms	3.9Arms	1.3Arms	5.2Arms	2.6Arms
Acceleration Force ²	138N (3	1.0lbs)	207N (46.5lbs)		276N (62lbs)		
Acceleration Current ²	5.2Arms	10.4Arms	5.2Arms	15.6Arms	5.2Arms	20.8Arms	10.4Arms
Force Constant (K _f)	27N/amp	13N/amp	40N/amp	13N/amp	53N/amp	13N/amp	27N/amp
Back EMF (K _e)	9V/m/s	4V/m/s	13V/m/s	4V/m/s	18V/m/s	4.4V/m/s	8.8V/m/s
Resistance 25°C³	8.4Ω	2.1Ω	13Ω	1.4Ω	17Ω	1Ω	4.2Ω
Inductance ³	9.2mH	2.3mH	14mH	1.5mH	18mH	1.2mH	4.6mH
Electric Time Constant	1.11	1.11ms		1.11ms 1.11ms			
Fundamental Motor Constant (K _m)	9.17N√W		11.23N√W		12.97N√W		
Magnetic Pitch (North-North)	90m	nm	90mm 90mm		90mm		

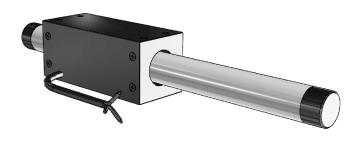
Is this the proper Linear Shaft Motor for your application? Use our SMART sizing program to assist in your decision.

This motor can be customized to fit your application demands; contact your application engineer for more information.

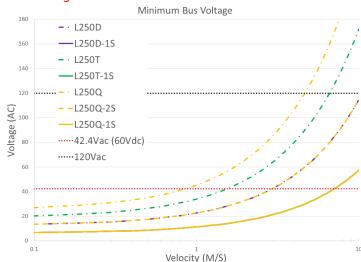
³ All winding parameters listed are measured line-to-line (phase-to-phase).

	L250D		L250T		L250Q		
Thermal Specs	L250D	L250D-1S	L250T	L250T-1S	L250Q	L250Q-1S	L250Q-2S
Max Phase Temperature ⁴	135°C (275°F)						
Thermal Resistance (Coil) (K _q)	7.8°C	7.8°C/W 5.2°C/W		3.9°C/W			

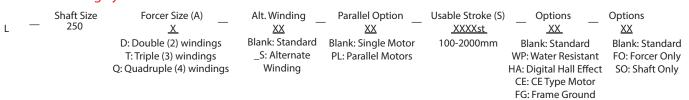
⁴The standard temperature difference between the coil and the forcer surface is 20°C.



Bus Voltage



Part Numbering System



These motors have not received a CE Declaration of Conformity, and as such are designated FGA.

¹ Based on a temp rise of coil surface of 110°K over 25°C ambient temperature stalled forcer, and no external cooling or heat sinking.

² Can be maintained for a maximum of 40 seconds. Higher forces and current possible for short periods of time, contact Nippon Pulse for more information.

	L250D		L250T		L250Q		
Forcer Specs	L250D	L250D-1S	L250T	L250T-1S	L250Q	L250Q-1S	L250Q-2S
Forcer Length (A)	120mm (4.72in)		165mm (6.5in)		210mm (8.27in)		
Forcer Width	50mm (1.97in)		50mm (1.97in)		50mm (1.97in)		
Forcer Screw Pitch (P)	105mm (4.1in)		150mm (5.9in)		195mm (7.7in)		
Forcer Weight	0.77kg (1.7lbs)		1.1kg (2.4lbs)		1.5kg (3.3lbs)		
Gap	2.0mm (0.08in)		2.0mm (0.08in)		2.0mm (0.08in)		
Screw	M6						
Tightening Torque	5.2 Nm						

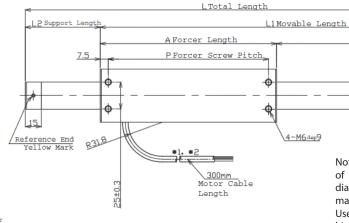
Tolerances are as follows: Dimension (mm) Tolerance (mm) 0 - 6 ±0.1 7 - 30 31 - 120 ±0.2 ±0.3 121 - 315 ±0.5 316 - 1000 ±0.8 1001 - 2000 ±1.2 2000 -±1.5 L = See Shaft Length

L1 = Usable Stroke + A L2 = See Support Length

A = See Forcer Length

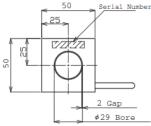
P = See Forcer Screw Pitch

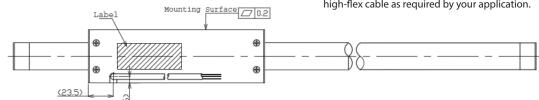
Unless otherwise specified, dimensions are in mm



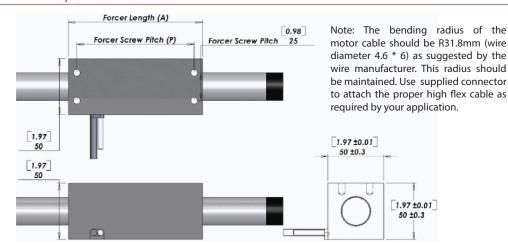
Note: Cable length 300mm. The bending radius of the motor cable should be 31.8mm (wire diameter 5.3 * 6) as suggested by the wire manufacturer. This radius should be maintained. Use supplied connector to attach the proper high-flex cable as required by your application.

SStroke Length





Hall Effect Specs

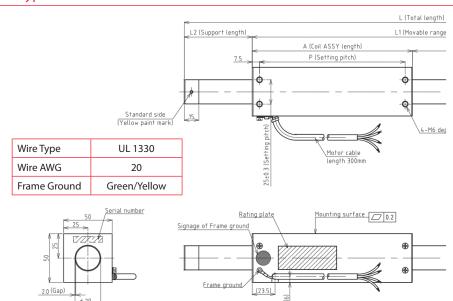


Sensor Cable Specs

Wire Type	UL 758	
Wire AWG	28	
VCC	White/Red	
GND	White/Black	
Sensor 1	Orange/Red	
Sensor 2	Orange/Black	
Sensor 3	Gray/Red	

The bending radius of the sensor cable should be R27.6mm (wire diameter 6.1 * 6) as suggested by the wire manufacturer. This radius should be maintained. Attach the proper high flex cable as required by your application.

FG Type Motor Cable



Standard Lead Wire

Wire Type	UL 2464FA	
Wire AWG	20	
U Phase	Red	
V Phase	White	
W Phase	Black	

300mm lead wire bare leads. The bending radius of the motor cable should be 31.8mm as suggested by the wire manufacturer.

CE Option - CE Type Lead Wire

CE
UL 1330
24
Red
White
Black

300mm lead wire leads. bare The bending radius of the motor cable should be 18.96mm as suggested by the wire manufacturer. FG type with insulating sheet between coils and case. Meets all requirements EN60034-1 (1998).

Forcer Spacing Distance

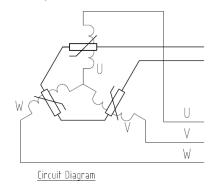
Spec	L250T	L250Q	
Forcer Spacing Distance	15r	nm	
Pole (N/S) Distance	45mm		
Forcer Length	165mm	210mm	
Flip Forcers	No	Yes	

Tandem L250D forcers are possible, but are equivalent to one (1) L250Q forcer and thus are not listed above.

Tandem Forcer



THM Option



4. Thermistor PTCSL20T071DBE(Vishay)

Support and Bending

Stroke	Support Length (L2)	Max. Bending
0~700	50mm	0.00mm
701~1000	70mm	0.30mm
1001~1500	70mm	0.70mm
1501~max	100mm	0.70mm

Shaft Diameter (D) - 20.5mm ±0.2

Total Length (L)=Stroke (S)+Forcer Length(A)+(Support Length (L2)x2)

Connector (Motor Cable)

Receptacle Housing	HLR-03V	
Plug Housing	HLP-03V	
Retainer	HLS-03V	
Pin Contact	SSM-21T-P1.4	
Socket Contact	SSF-21T-P1.4	

To be installed by the user.

Thermocouple

Thermal sensor Thermocouple K type (marked each phase name) Attached to the surface of inside of coil Length 3000mm

Shaft Length (L)

1850

1900

1950

2000

2170mm (85.4in)

2220mm (87.4in)

2270mm (89.4in)

2320mm (91.3in)

Stroke L250D L250T L250Q 410mm (16.1in) 100 320mm (12.6in) 365mm (14.4in) 150 370mm (14.6in) 415mm (16.3in) 460mm (18.1in) 200 420mm (16.5in) 465mm (18.3in) 510mm (20.1in) 250 470mm (18.5in) 515mm (20.3in) 560mm (22in) 300 520mm (20.5in) 565mm (22.2in) 610mm (24in) 570mm (22.4in) 615mm (24.2in) 660mm (26in) 350 400 620mm (24.4in) 665mm (26.2in) 710mm (28in) 450 670mm (26.4in) 715mm (28.1in) 760mm (29.9in) 500 720mm (28.3in) 765mm (30.1in) 810mm (31.9in) 550 770mm (30.3in) 815mm (32.1in) 860mm (33.9in) 600 820mm (32.3in) 865mm (34.1in) 910mm (35.8in) 650 870mm (34.3in) 915mm (36in) 960mm (37.8in) 700 920mm (36.2in) 965mm (38in) 1010mm (39.8in) 750 1010mm (39.8in) 1055mm (41.5in) 1100mm (43.3in) 800 1060mm (41.7in) 1105mm (43.5in) 1150mm (45.3in) 850 1110mm (43.7in) 1155mm (45.5in) 1200mm (47.2in) 900 1160mm (45.7in) 1250mm (49.2in) 1205mm (47.4in) 950 1210mm (47.6in) 1255mm (49.4in) 1300mm (51.2in) 1000 1260mm (49.6in) 1305mm (51.4in) 1350mm (53.1in) 1050 1400mm (55.1in) 1310mm (51.6in) 1355mm (53.3in) 1100 1360mm (53.5in) 1405mm (55.3in) 1450mm (57.1in) 1150 1410mm (55.5in) 1455mm (57.3in) 1500mm (59.1in) 1200 1460mm (57.5in) 1505mm (59.3in) 1550mm (61in) 1250 1510mm (59.4in) 1600mm (63in) 1555mm (61.2in) 1300 1560mm (61.4in) 1605mm (63.2in) 1650mm (65in) 1350 1610mm (63.4in) 1655mm (65.2in) 1700mm (66.9in) 1750mm (68.9in) 1400 1660mm (65.4in) 1705mm (67.1in) 1450 1710mm (67.3in) 1755mm (69.1in) 1800mm (70.9in) 1850mm (72.8in) 1500 1760mm (69.3in) 1805mm (71.1in) 1550 1870mm (73.6in) 1915mm (75.4in) 1960mm (77.2in) 1600 1920mm (75.6in) 1965mm (77.4in) 2010mm (79.1in) 1650 1970mm (77.6in) 2015mm (79.3in) 2060mm (81.1in) 1700 2020mm (79.5in) 2065mm (81.3in) 2110mm (83.1in) 1750 2070mm (81.5in) 2115mm (83.3in) 2160mm (85in) 1800 2120mm (83.5in) 2165mm (85.2in) 2210mm (87in)

Shaft Mass

Stroke	L250D	L250T	L250Q
100	0.9kg (2lb)	1.1kg (2.4lb)	1.2kg (2.6lb)
150	1.1kg (2.4lb)	1.2kg (2.6lb)	1.4kg (3.1lb)
200	1.2kg (2.6lb)	1.4kg (3.1lb)	1.6kg (3.5lb)
250	1.4kg (3.1lb)	1.6kg (3.5lb)	1.7kg (3.7lb)
300	1.6kg (3.5lb)	1.7kg (3.7lb)	1.9kg (4.2lb)
350	1.8kg (4lb)	1.9kg (4.2lb)	2.1kg (4.6lb)
400	1.9kg (4.2lb)	2.1kg (4.6lb)	2.2kg (4.9lb)
450	2.1kg (4.6lb)	2.3kg (5.1lb)	2.4kg (5.3lb)
500	2.3kg (5.1lb)	2.4kg (5.3lb)	2.6kg (5.7lb)
550	2.4kg (5.3lb)	2.6kg (5.7lb)	2.8kg (6.2lb)
600	2.6kg (5.7lb)	2.8kg (6.2lb)	2.9kg (6.4lb)
650	2.8kg (6.2lb)	2.9kg (6.4lb)	3.1kg (6.8lb)
700	3kg (6.6lb)	3.1kg (6.8lb)	3.3kg (7.3lb)
750	3.2kg (7.1lb)	3.4kg (7.5lb)	3.5kg (7.7lb)
800	3.4kg (7.5lb)	3.5kg (7.7lb)	3.7kg (8.2lb)
850	3.5kg (7.7lb)	3.7kg (8.2lb)	3.8kg (8.4lb)
900	3.7kg (8.2lb)	3.9kg (8.6lb)	4kg (8.8lb)
950	3.9kg (8.6lb)	4kg (8.8lb)	4.2kg (9.3lb)
1000	4.1kg (9lb)	4.2kg (9.3lb)	4.4kg (9.7lb)
1050	4.2kg (9.3lb)	4.4kg (9.7lb)	4.5kg (9.9lb)
1100	4.4kg (9.7lb)	4.6kg (10.1lb)	4.7kg (10.4lb)
1150	4.6kg (10.1lb)	4.7kg (10.4lb)	4.9kg (10.8lb)
1200	4.7kg (10.4lb)	4.9kg (10.8lb)	5.1kg (11.2lb)
1250	4.9kg (10.8lb)	5.1kg (11.2lb)	5.2kg (11.5lb)
1300	5.1kg (11.2lb)	5.2kg (11.5lb)	5.4kg (11.9lb)
1350	5.3kg (11.7lb)	5.4kg (11.9lb)	5.6kg (12.3lb)
1400	5.4kg (11.9lb)	5.6kg (12.3lb)	5.7kg (12.6lb)
1450	5.6kg (12.3lb)	5.8kg (12.8lb)	5.9kg (13lb)
1500	5.8kg (12.8lb)	5.9kg (13lb)	6.1kg (13.4lb)
1550	6kg (13.2lb)	6.2kg (13.7lb)	6.3kg (13.9lb)
1600	6.2kg (13.7lb)	6.3kg (13.9lb)	6.5kg (14.3lb)
1650	6.3kg (13.9lb)	6.5kg (14.3lb)	6.6kg (14.6lb)
1700	6.5kg (14.3lb)	6.7kg (14.8lb)	6.8kg (15lb)
1750	6.7kg (14.8lb)	6.8kg (15lb)	7kg (15.4lb)
1800	6.9kg (15.2lb)	7kg (15.4lb)	7.2kg (15.9lb)
1850	7kg (15.4lb)	7.2kg (15.9lb)	7.3kg (16.1lb)
1900	7.2kg (15.9lb)	7.4kg (16.3lb)	7.5kg (16.5lb)
1950	7.4kg (16.3lb)	7.5kg (16.5lb)	7.7kg (17lb)
2000	7.6kg (16.8lb)	7.7kg (17lb)	7.9kg (17.4lb)

Additional stroke lengths up to 2500 are available. Contact Nippon Pulse for more information.

2260mm (89in)

2310mm (90.9in)

2360mm (92.9in)

2410mm (94.9in)

2215mm (87.2in)

2265mm (89.2in)

2315mm (91.1in)

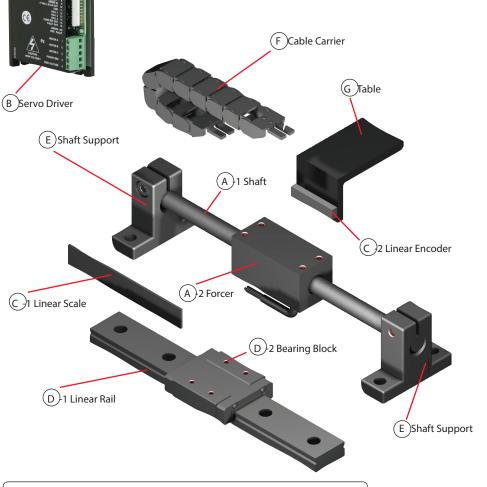
2365mm (93.1in)



The design of the Linear Shaft Motor allows you to replace traditional linear motion systems, such as a standard ball screw, with the Linear Shaft Motor and achieve higher speed and resolution.

To achieve the highest performance with the Linear Shaft Motor system, the entire system structure must be optimized.

Be aware there are various design considerations which are somewhat different from traditional servo system practices. These are the main components needed to make a Linear Shaft Motor system, as well as factors to consider when designing a system.



Configuring the Linear Shaft Motor

To configure a system using the Linear Shaft Motor, the following peripheral devices are required:

- A. Linear Shaft Motor
- B. Servo Driver
- C. Linear encoder (optical or magnetic)

Item D (Linear Guide) is a necessary part of a system, but consideration must be given to the application, demand specifications, environmental conditions, and which will be moving—the forcer or the shaft.

The other items, E through G, are optional and will need to be selected depending on the application.

System Design Linear Shaft Motor

Steps to putting together a Linear Shaft Motor System

Choose the Linear Shaft Motor based on force and stroke requirements.

Choose the shaft supports based on design and motor specifications.

Choose the linear guide (bearings) based on cost and smoothness (performance) constraints.

Choose the linear encoder to achieve the required position resolution.

Choose the servo driver to match the power requirements of the Linear Shaft Motor.

Choose the OTL, limit switches/other components and assemble the Linear Shaft Motor system.